

Imaging seismic rupture process by Markov Chain Monte Carlo technique - the case of Rudna (Poland) copper mine events

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Plan of the talk

- ❖ Numerical background
 - ★ Inversion techniques
 - ★ Markov Chain Monte Carlo
 - ★ Pseudo-spectral parametrization
- ❖ Relative Source Time Function
 - ★ Information on rupture process
 - ★ Empirical Green Function
- ❖ Mining Induced Events - case study
 - ★ Local seismic network
 - ★ Examples

Inverse problem - Indirect Measurements

$$\mathbf{d}^{obs} \implies \mathbf{m}$$

Solution

$$||\mathbf{d}^{obs} - \mathbf{d}^{th}(\mathbf{m})|| + \lambda ||\mathbf{m}^{ml} - \mathbf{m}^{apr}|| = \min$$

Errors

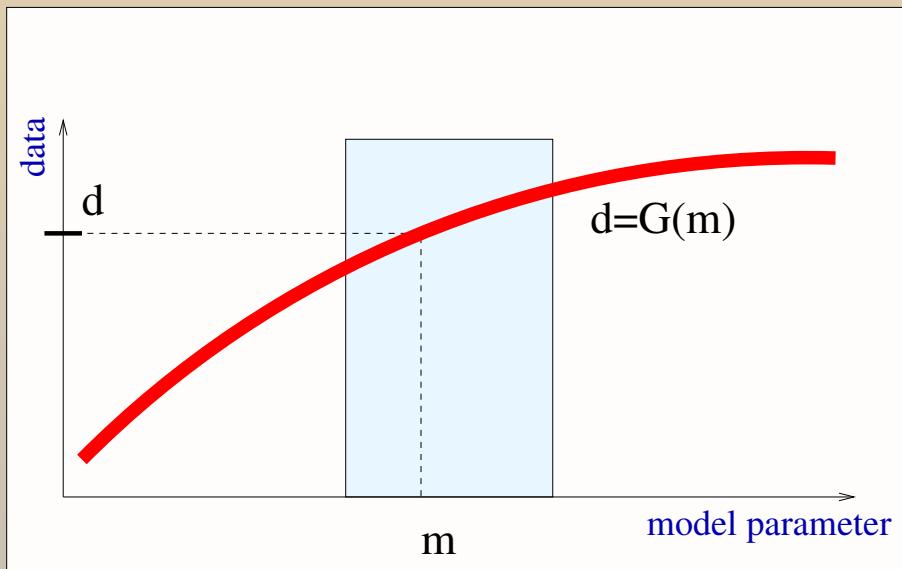
$$\mathbf{m}^{true} = \mathbf{m}^{ml} + \epsilon_{\mathbf{m}}$$

$$\epsilon_{\mathbf{m}} = ???$$

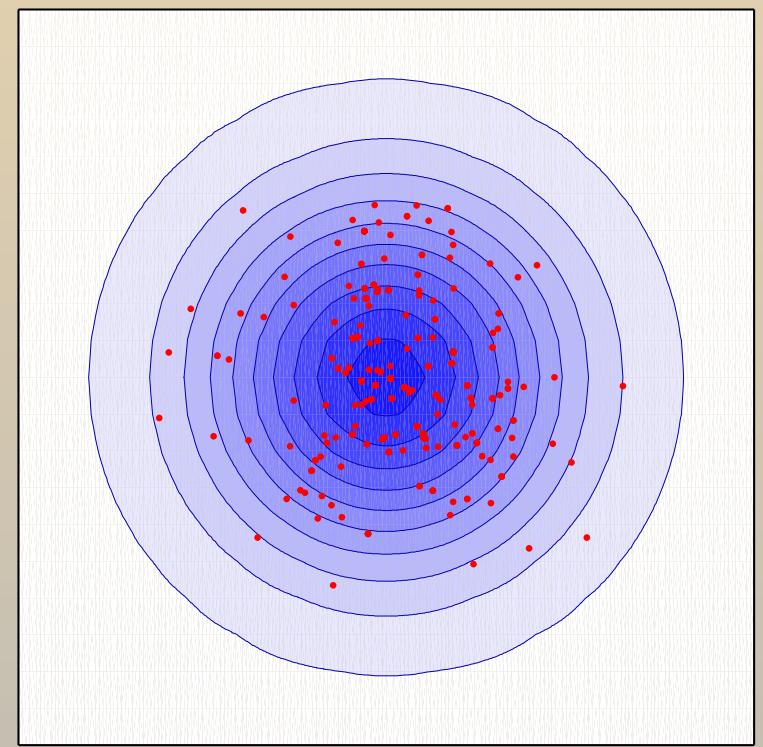
Inversion Algorithms

Method	Advantages	Limitations
Algebraic (LSQR)	- Simplicity	- Only linear problems
$\mathbf{m}^{ml} = (\mathbf{G}^T \mathbf{G} + \gamma \mathbf{I})^{-1} \mathbf{G}^T \cdot \mathbf{d}^{obs}$	- Large scale problems	- Lack of robustness
Optimization	- Simplicity	- Difficult error estimation
$\ \mathbf{G}(\mathbf{m}) - \mathbf{d}^{obs}\ + \lambda \ \mathbf{m} - \mathbf{m}^a\ = \min$	- Fully nonlinear	
Bayesian	- Fully nonlinear	- More complex theory
$\sigma(\mathbf{m}) = f(\mathbf{m}) L(\mathbf{m}, \mathbf{d}^{obs})$	- Full error handling	- Requires efficient sampler

Inversion algorithms

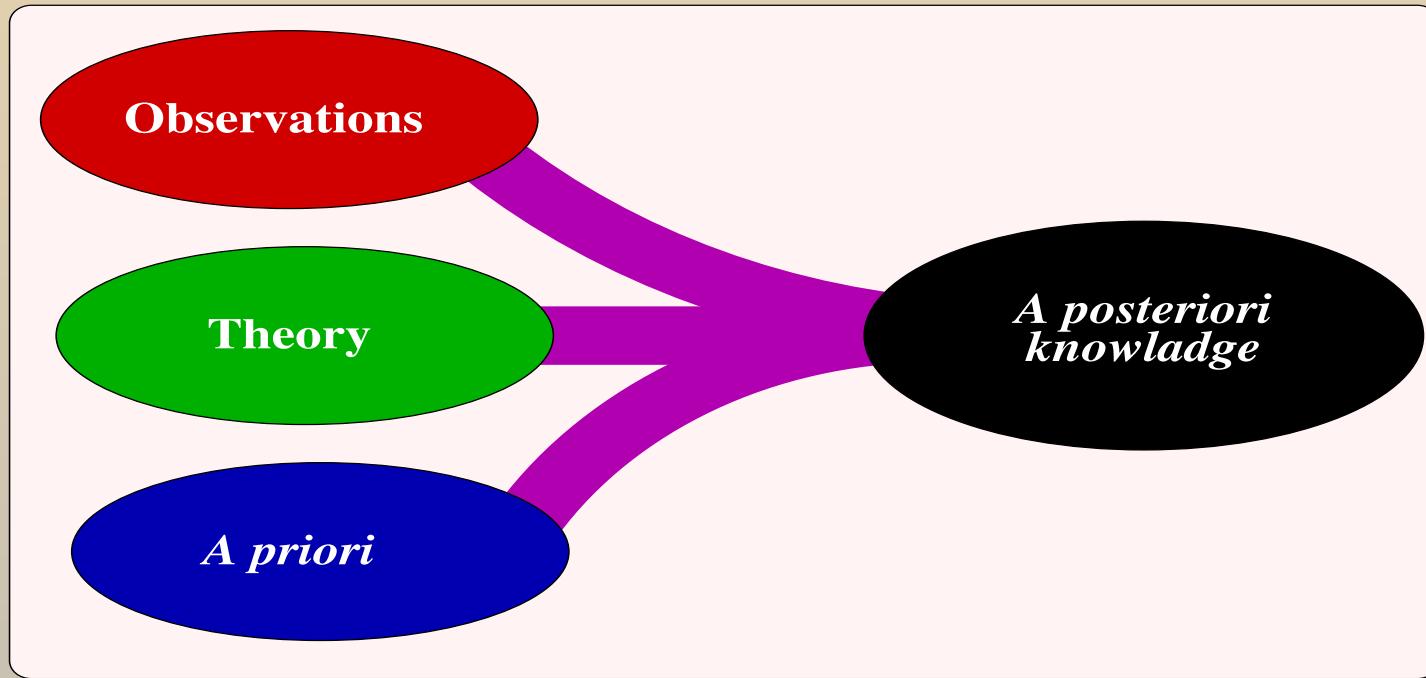


Back projection



Model space search

Bayesian Inversion - Basic Ideas



$$p_{post}(\mathbf{m}|\mathbf{d}) = \frac{p_{th}(\mathbf{d}|\mathbf{m})p_{apr}(\mathbf{m})}{p_{obs}(\mathbf{d})}$$

Bayesian Inversion

A posteriori pdf

$$\sigma(\mathbf{m}) = f(\mathbf{m})L(\mathbf{m}, \mathbf{d})$$

- ◆ f - A priori pdf (prob. dens. funct.)
- ◆ L - Likelihood function

Errors independent of \mathbf{m} and \mathbf{d}

$$\mathbf{d}^{th} = \mathbf{G}(\mathbf{m})$$

$$\sigma(\mathbf{m}) = f(\mathbf{m}) \exp(-||\mathbf{d}^{obs} - \mathbf{G}(\mathbf{m})||)$$

Probabilistic approach

A posteriori pdf $\sigma(m, d)$:

- ◆ always exists
- ◆ is unique
- ◆ describes all information
- ◆ is the **solution** of an inverse problem

When and why we need to use this approach ???

ERROR ANALYSIS !!!

Examination of $\sigma(m)$

- ◆ Searching *Maximum Likelihood* solution
 - ★ Gradient methods
 - ★ Monte Carlo - Global Optimization
- ◆ Sampling over regular grid
- ◆ **Random (Monte Carlo) Sampling**

Monte Carlo sampling

Monte Carlo sampling

$$\{\mathbf{m}_1, \mathbf{m}_2, \dots, \mathbf{m}_N\}$$

$$N_{[\mathbf{m} - \Delta, \mathbf{m} + \Delta]} \sim \sigma(\mathbf{m})$$

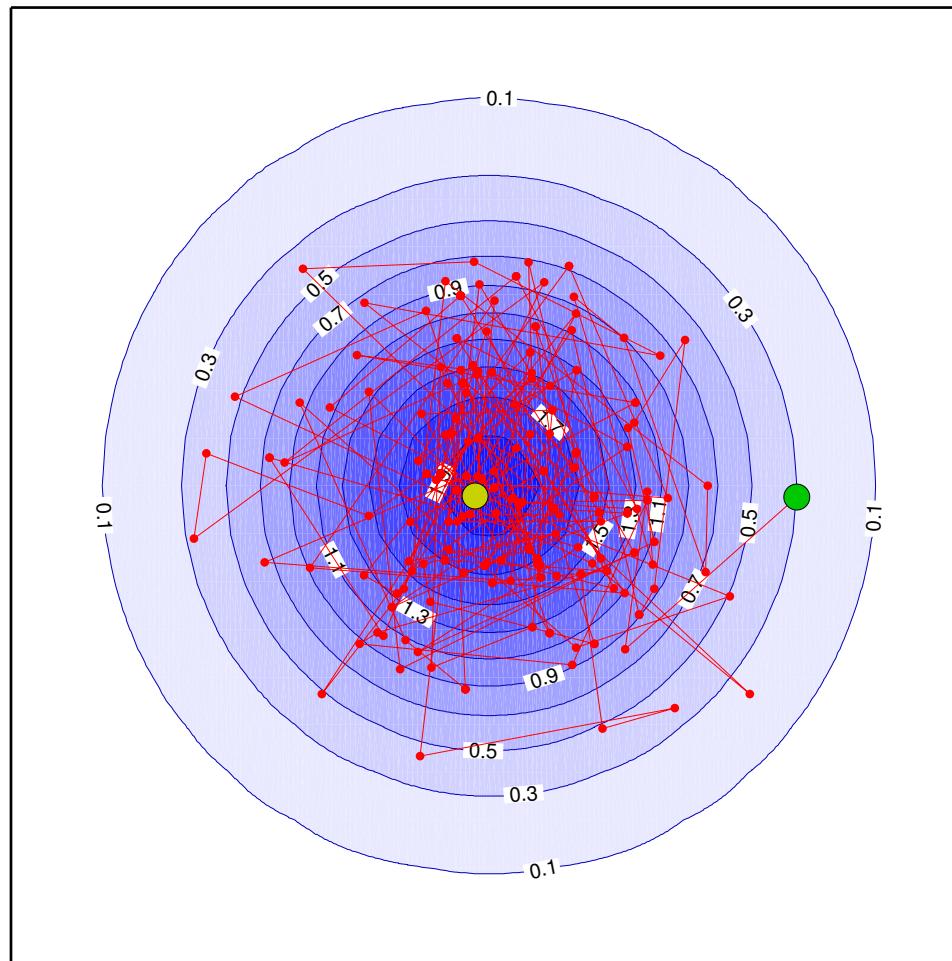
Solution

❖ $\mathbf{m}^{ml} = \mathbf{m}_i : \sigma_M(\mathbf{m}_i) = \max$

❖ $\mathbf{m}^{avr} = \sum_{samples} \mathbf{m}_s$

❖ $\epsilon_{\mathbf{m}} = \sum_{samples} (\mathbf{m}^{avr} - \mathbf{m}_s)^2$

Markov Chain Monte Carlo technique



Elements of seismic tomography

Far field:

$$u_i^{obs}(t, \mathbf{r}) = \int_{t'} \int_{\Sigma} \mathcal{G}_i(t - t', \mathbf{r}, \mathbf{r}') S(t', \mathbf{r}') d\mathbf{r}' dt'$$

$$u_i^{obs}(t) = \int_{t'} \mathcal{G}_i(t - t') \bar{S}_i(t') dt'$$

Seismic tomography - two step inversion

Apparent STF

$$\bar{S}_i(t) \approx \int_{\Sigma} S(t + \delta_i(\mathbf{r}'), \mathbf{r}') d\mathbf{r}'$$

Two steps inversion

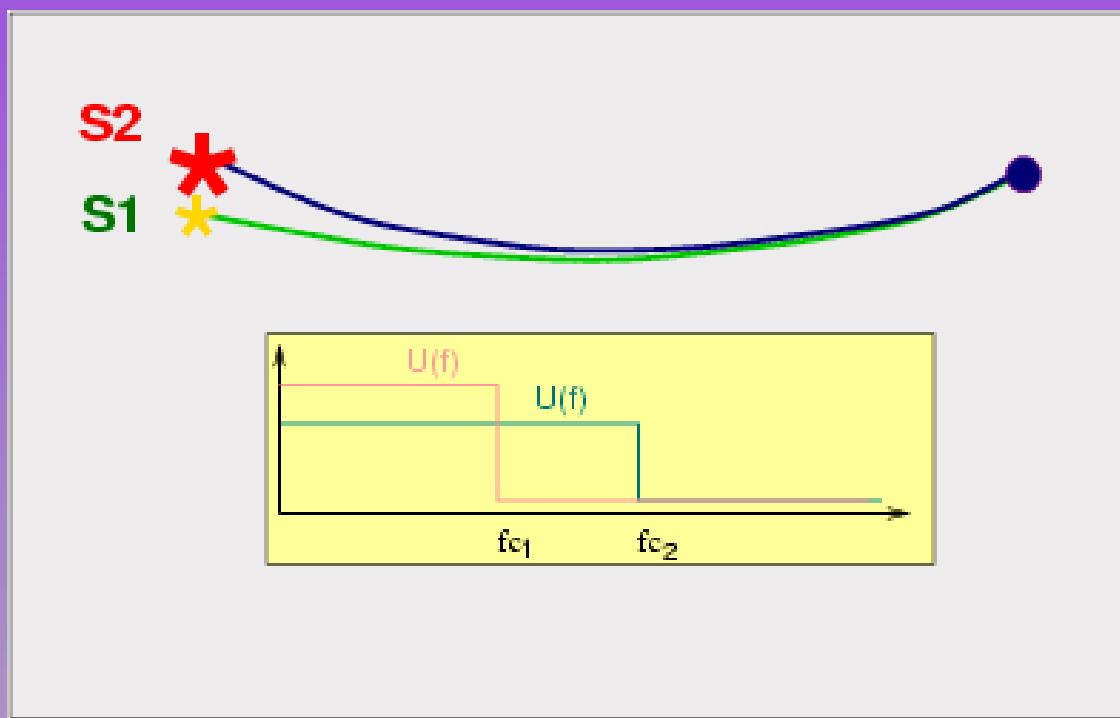
$$u_i^{obs}(t) \implies \bar{S}_i(t') \implies S(t, \mathbf{r})$$

Apparent STF

$$u_i^{obs}(t) = \int_{t'} \mathcal{G}_i(t - t') \bar{S}_i(t') dt'$$

-
- ❖ Aproximation \mathcal{G} : (e.g. Empirical Green Function (EGF))
 - ❖ Discretization $\bar{S}(t) \implies \{m_1, m_2, \dots\}$
 - ❖ Constraints
 - ★ causality
 - ★ finit duration
 - ★ positivity
 - ★ limited frequency band

Empirical Green Function



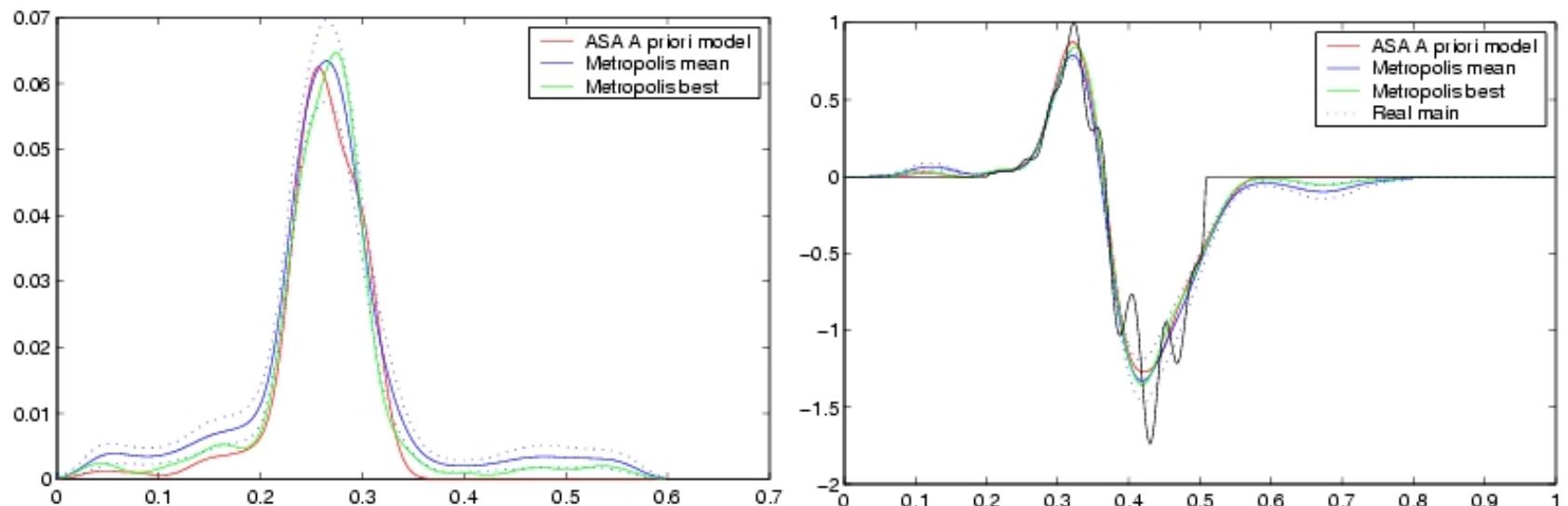
Discretization

$$\bar{S}(t) = \sum_i a_i \phi_i(t)$$

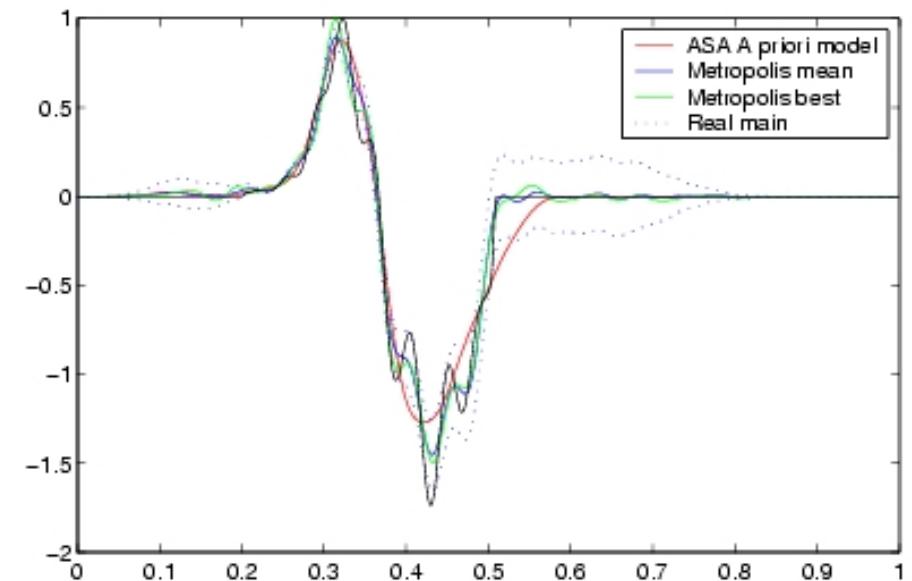
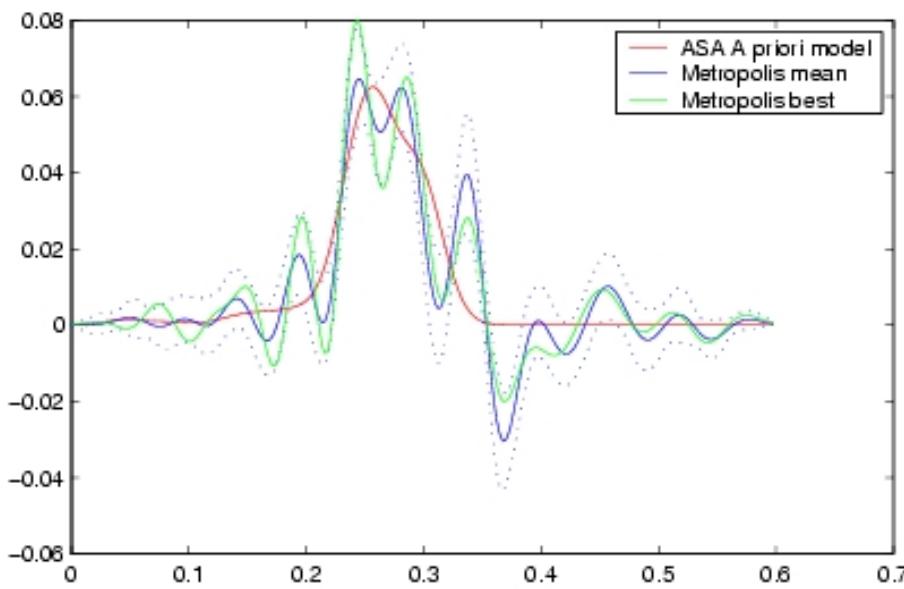
$$\phi_i(t) = \begin{cases} \delta(t - t_i) \\ \exp\left(-\frac{1}{2}(t - t_i)^2\right) \\ \sin(\omega_i t) \end{cases}$$

$$\bar{S}(t) \equiv \bar{S}(\mathbf{a}) \leftrightarrow \{a_i\}$$

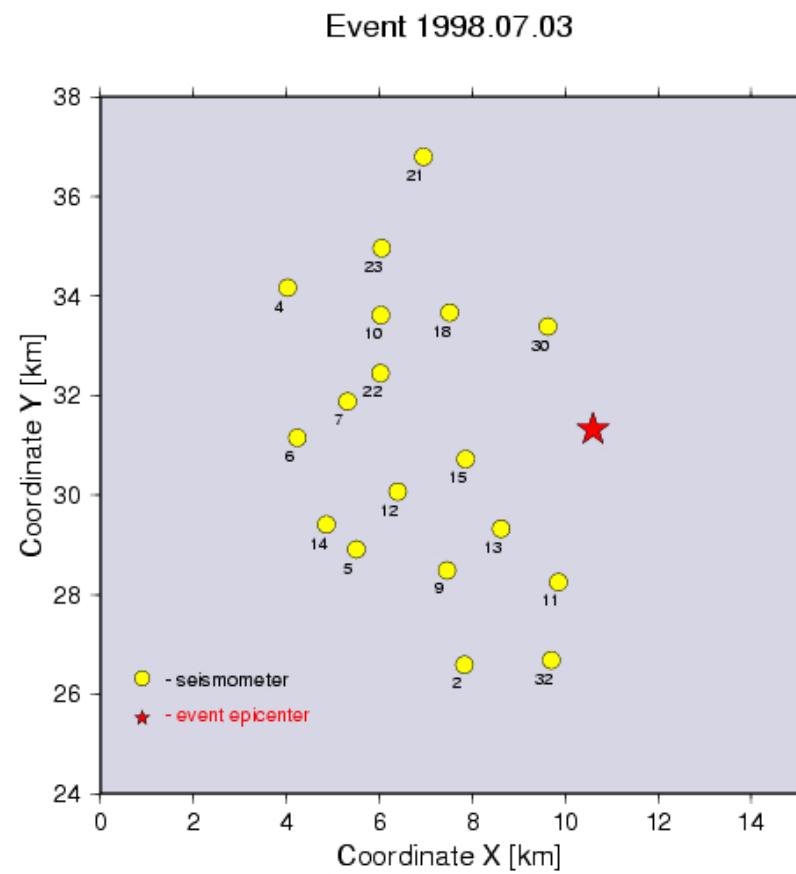
Positivity constraint



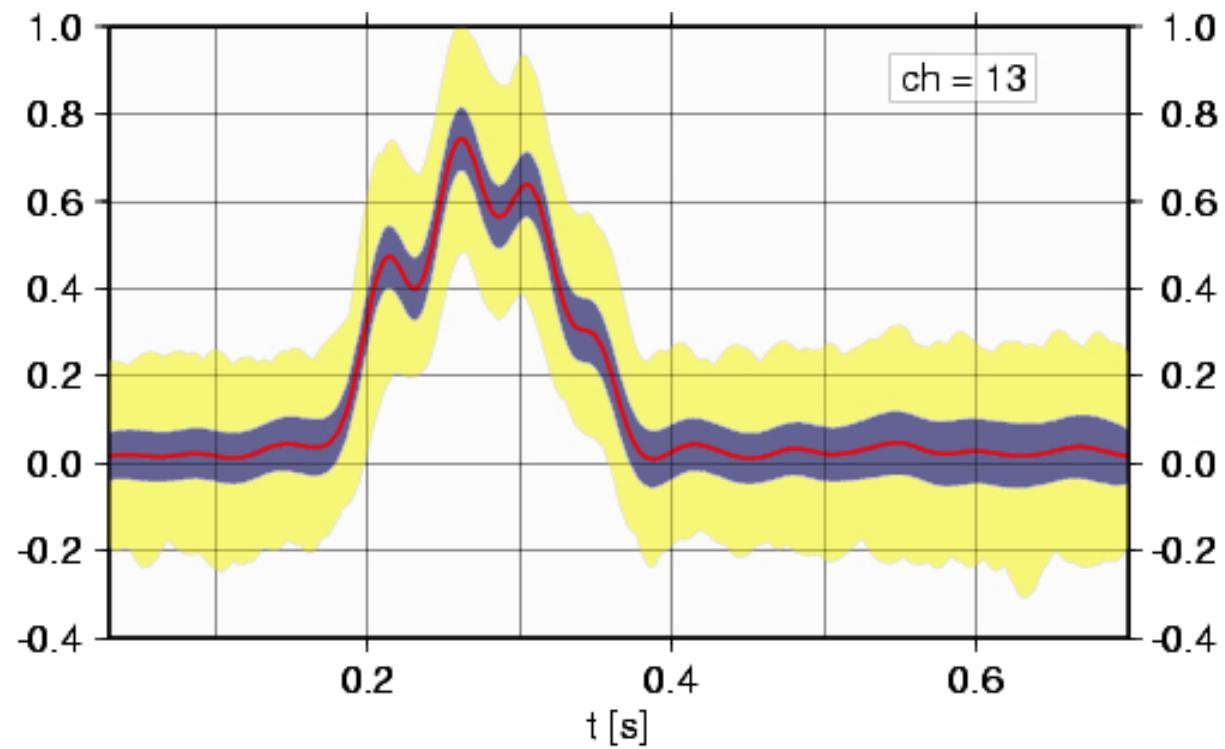
No constraint



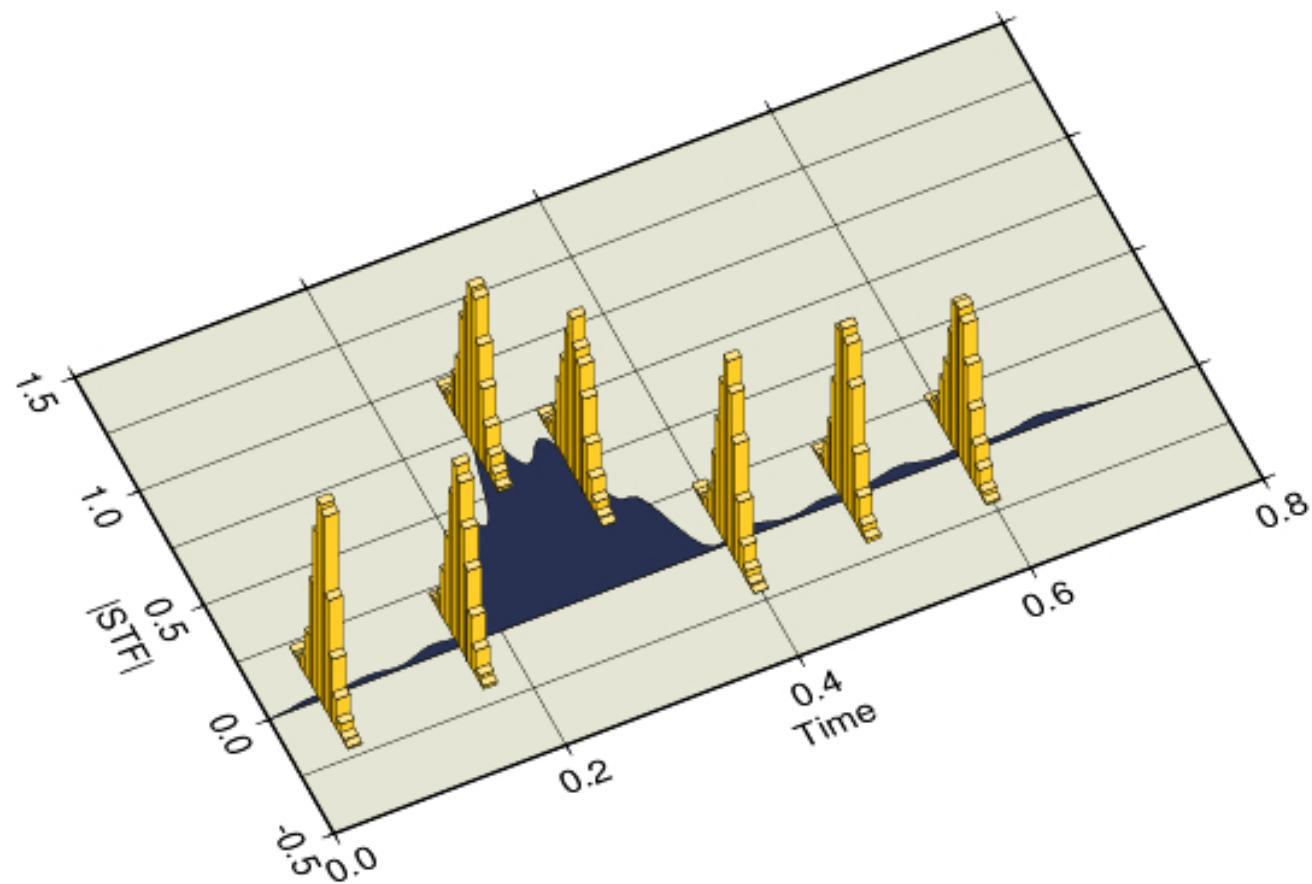
Station distribution



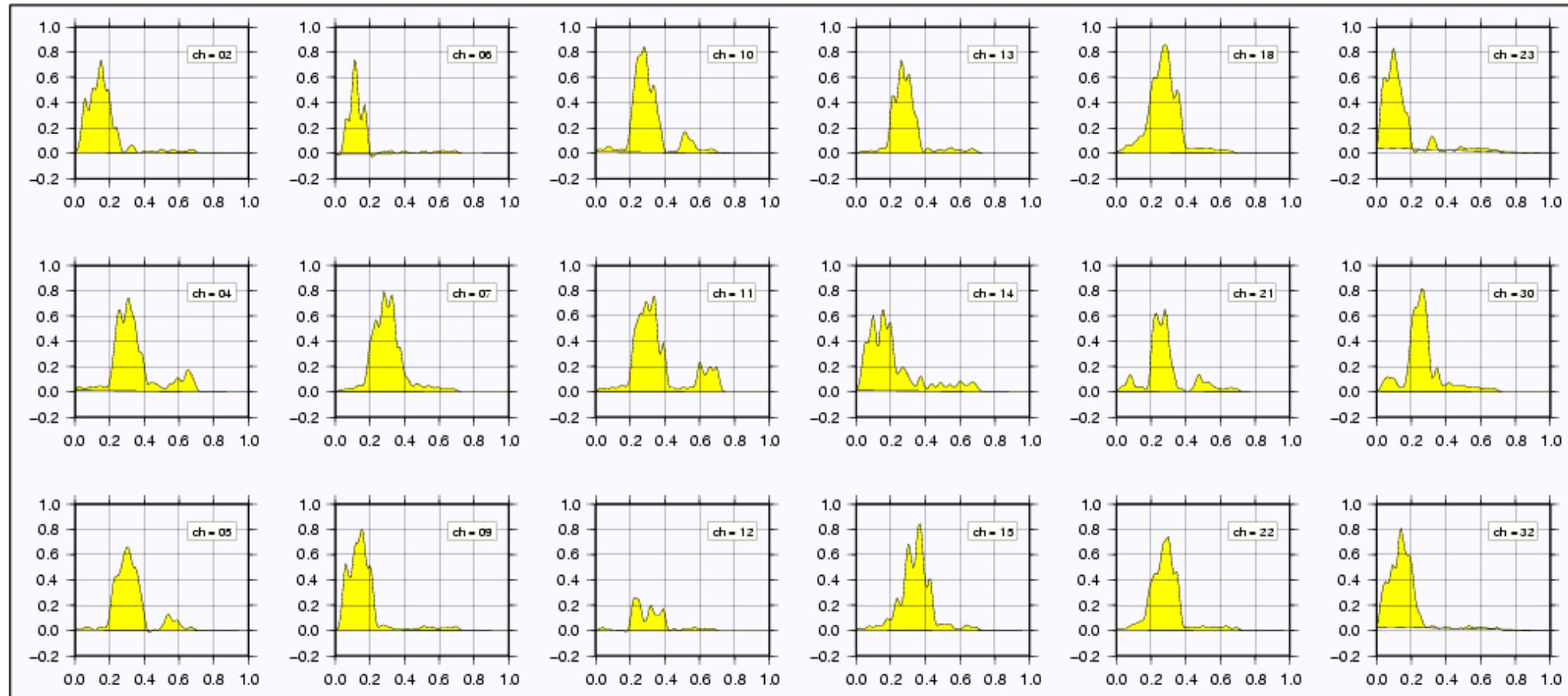
STF - channel 13



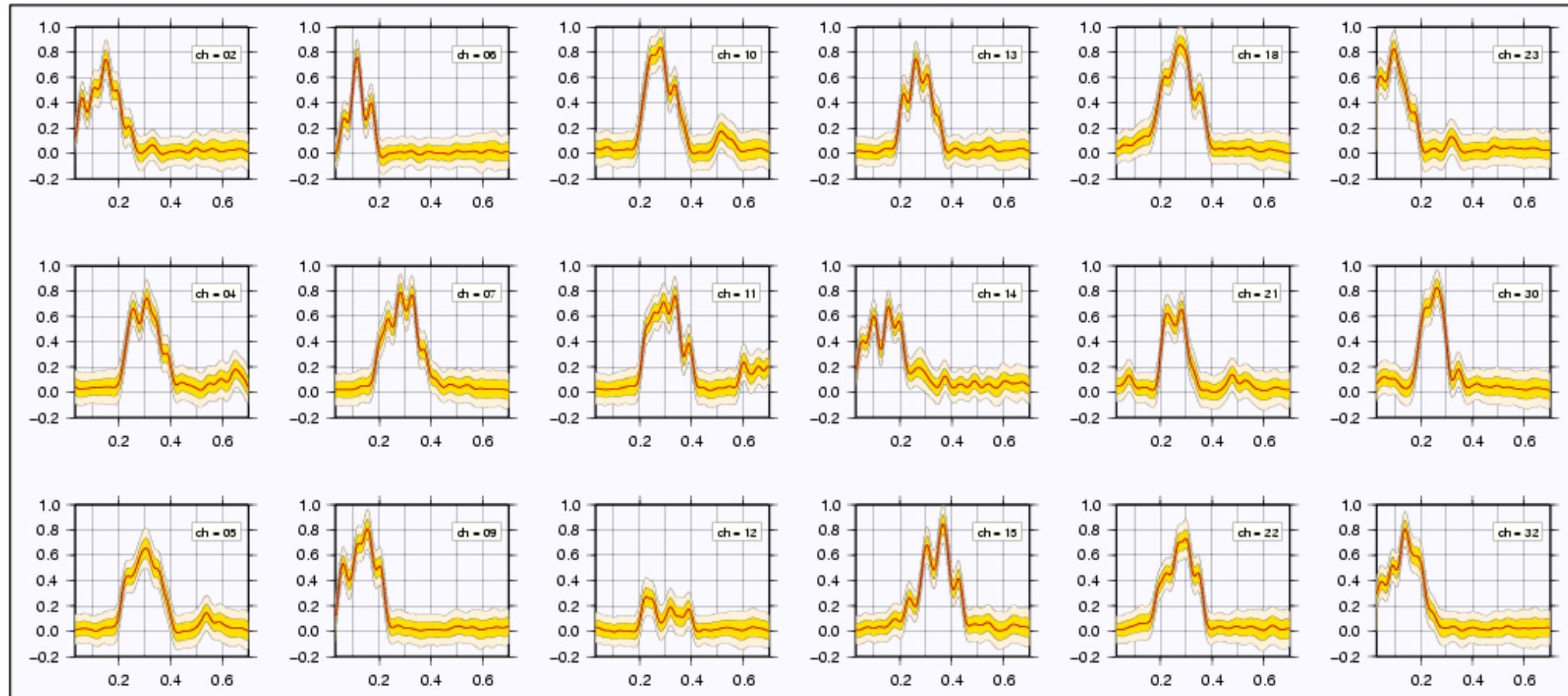
STF - channel 13



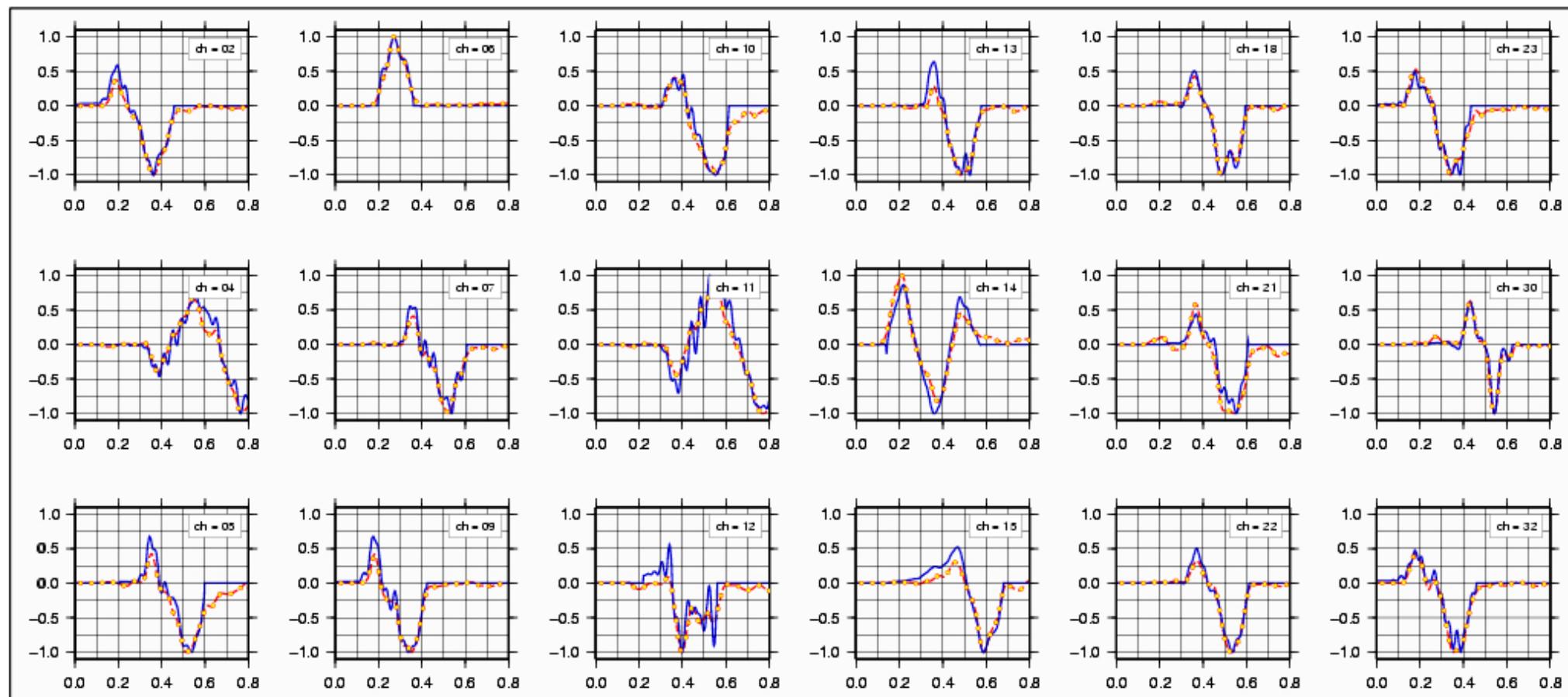
All channels



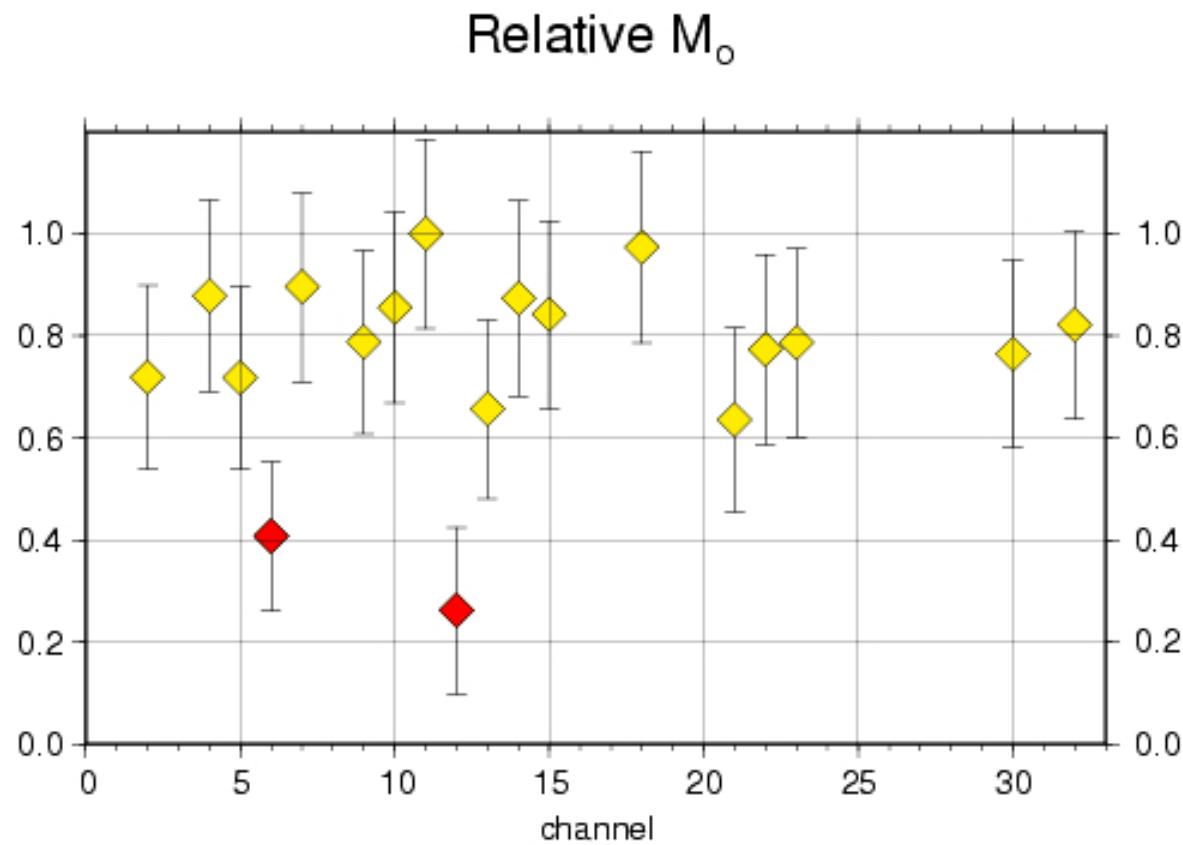
STF- errors



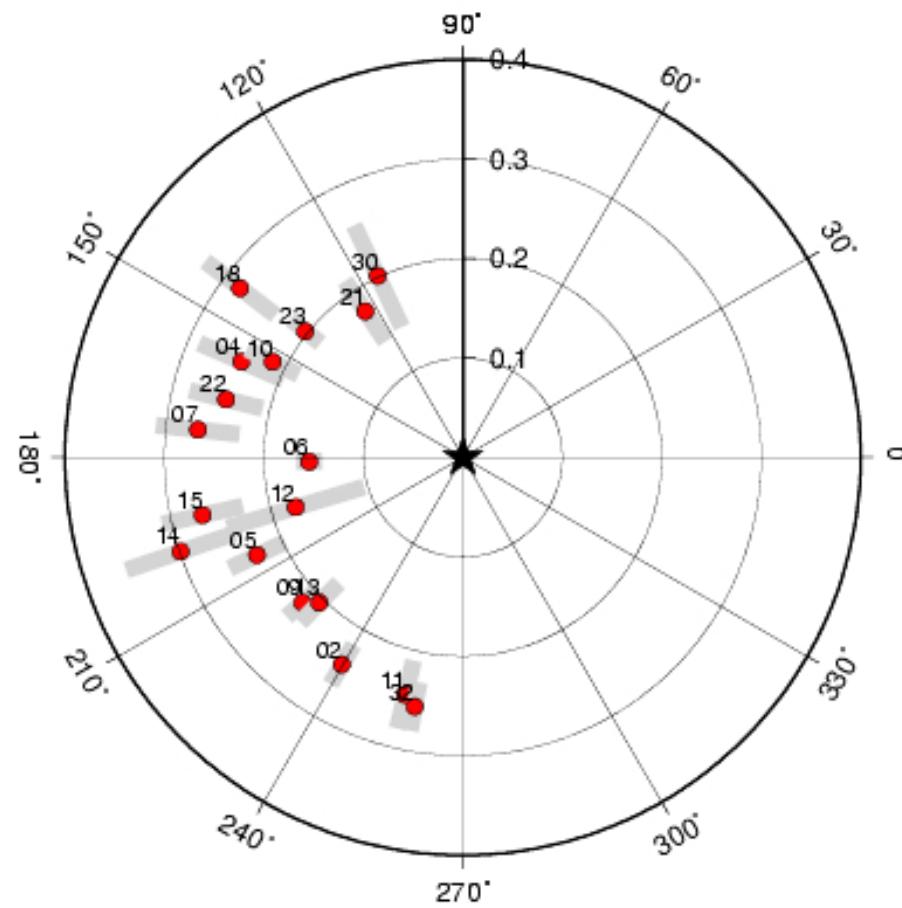
Synthetic vs. recorded seismograms



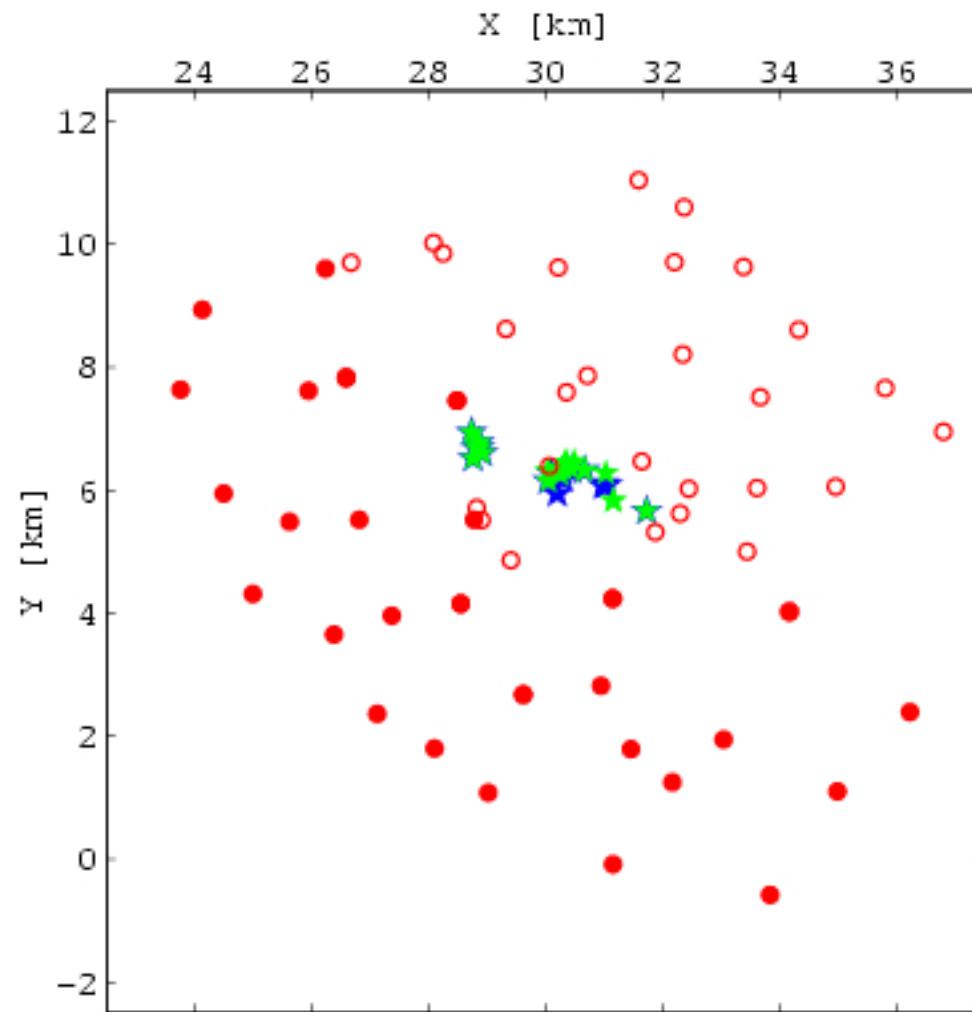
Moment sejsmiczny



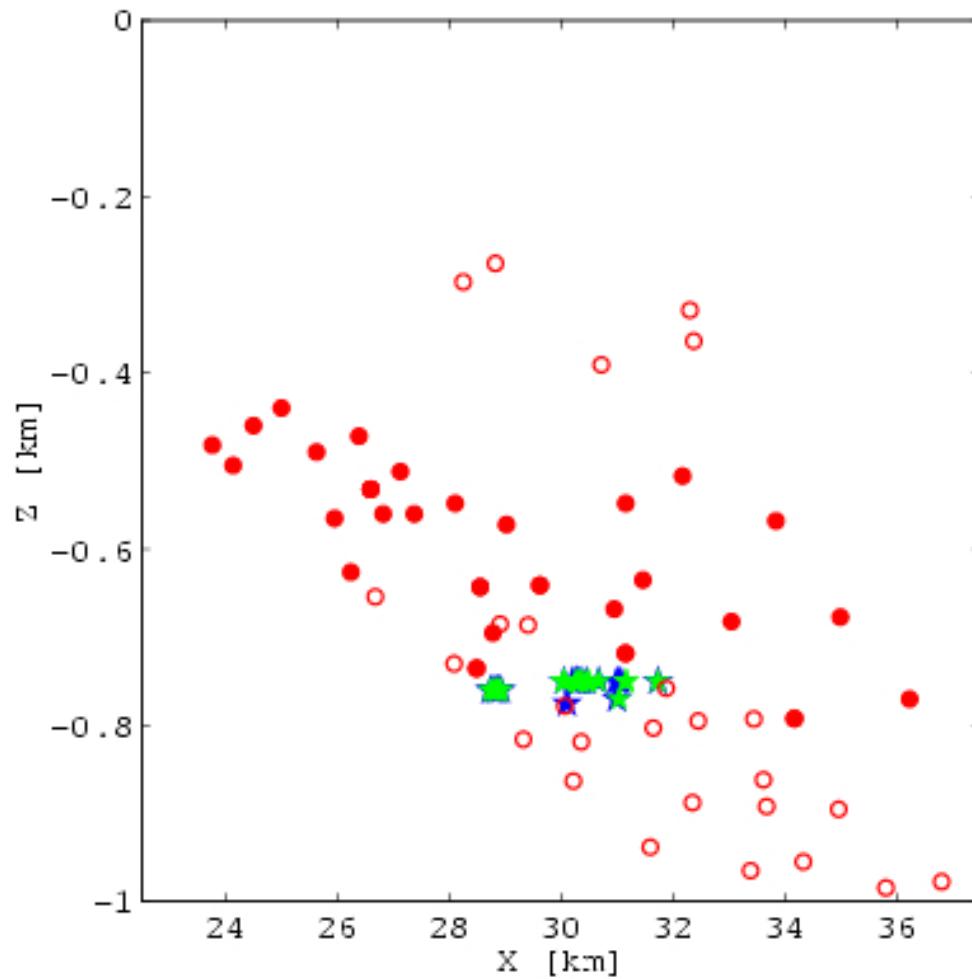
Rozkład kątowy



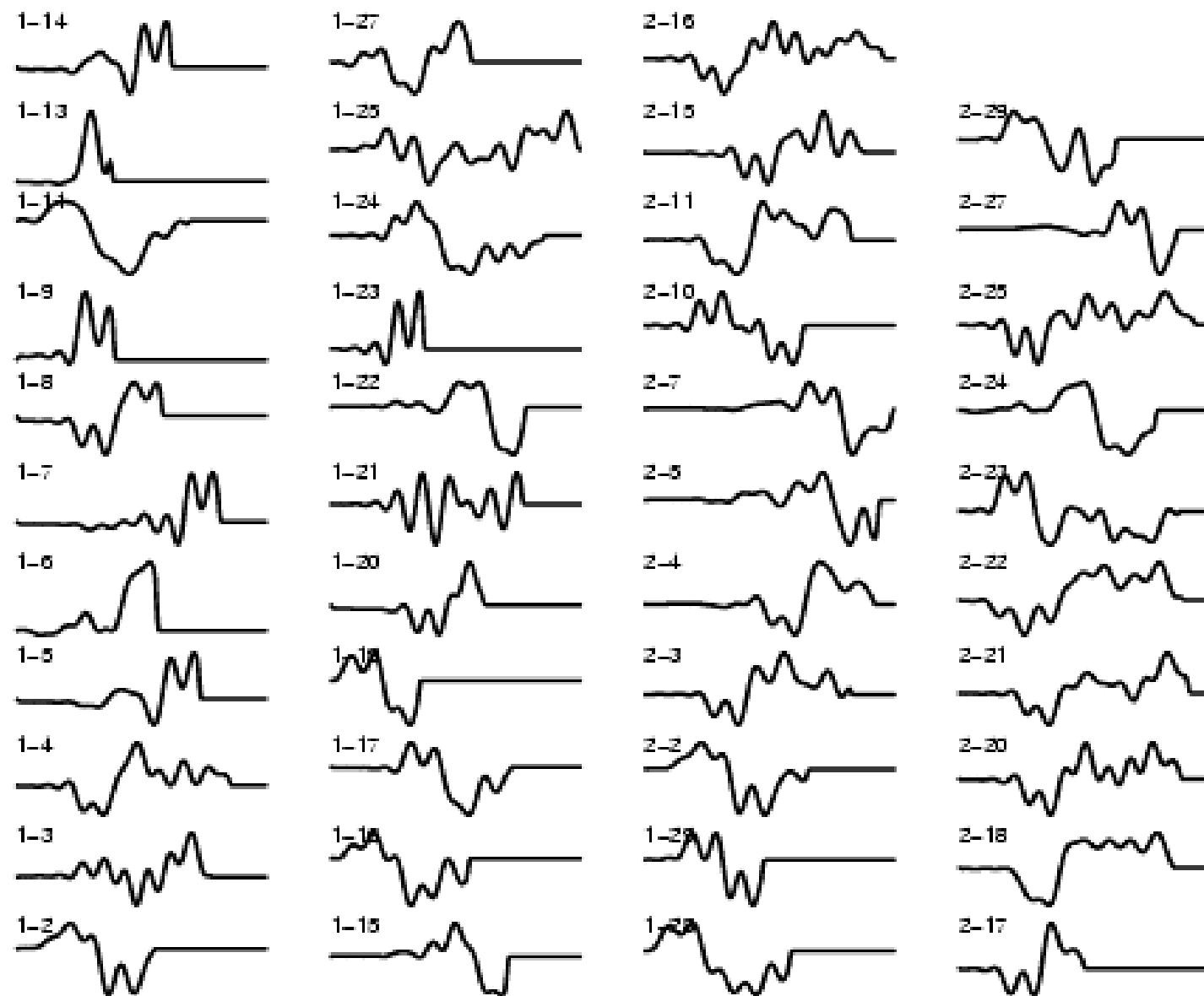
Station distribution



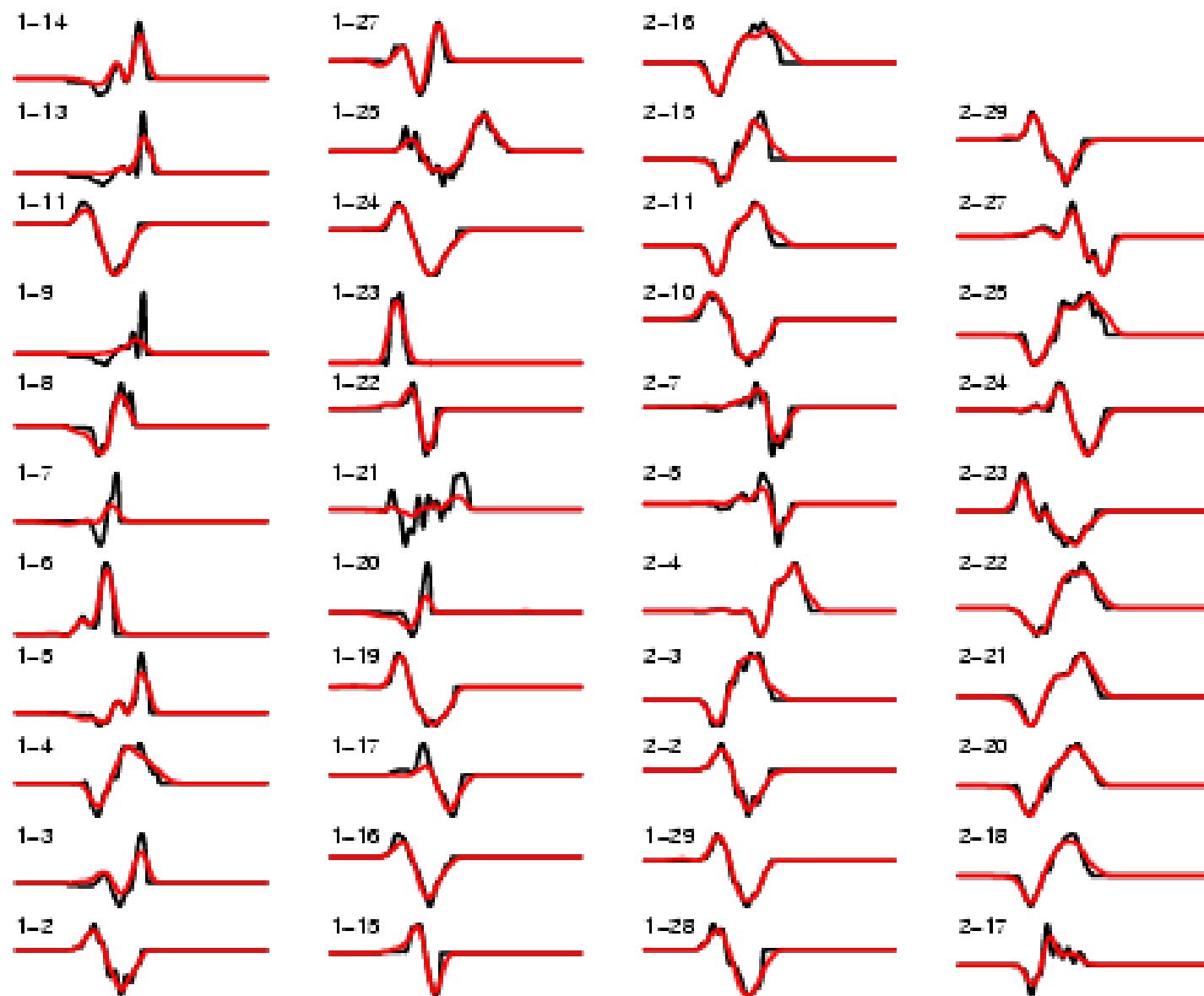
Station distribution



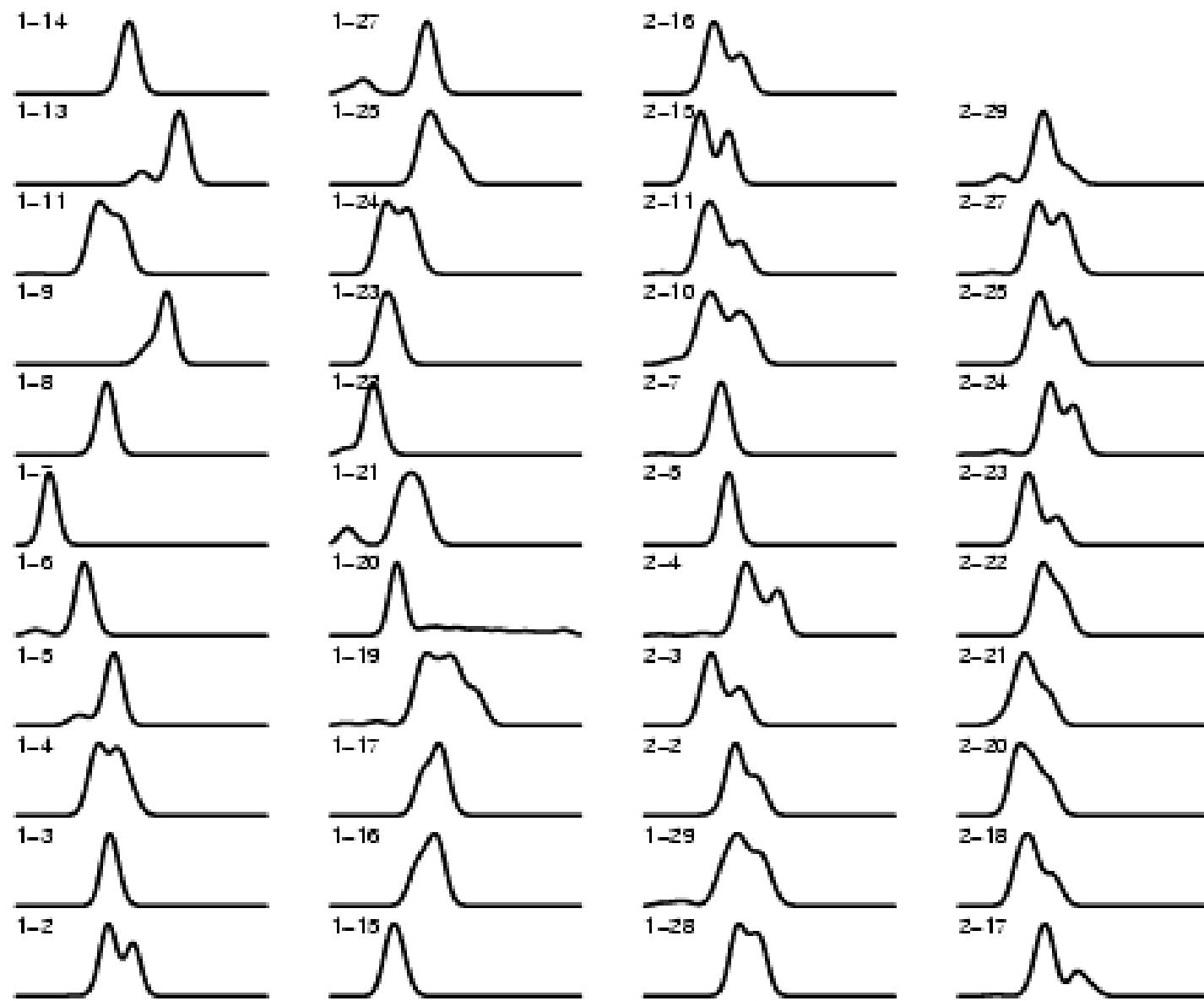
Empirical Green Functions



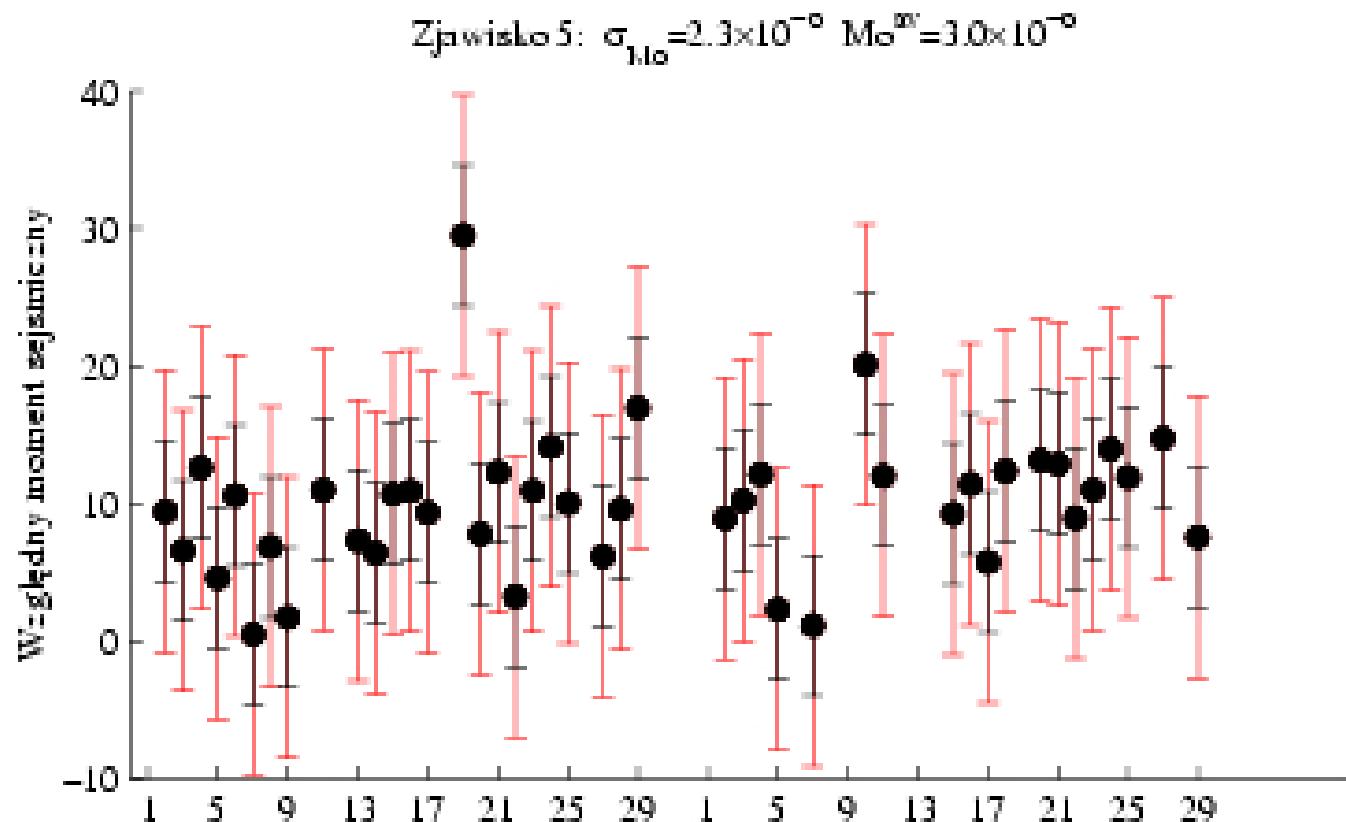
Synthetics/Main



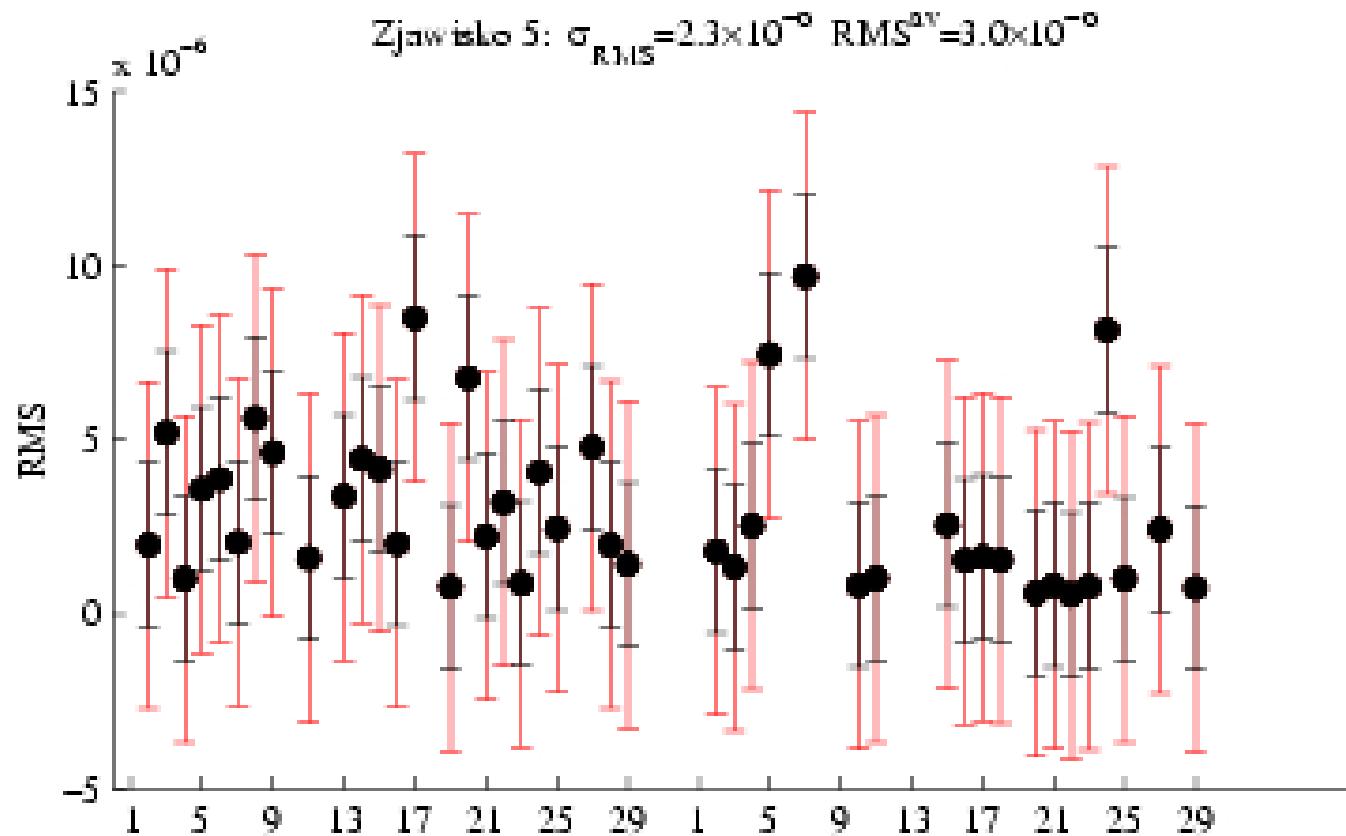
Source Time Function



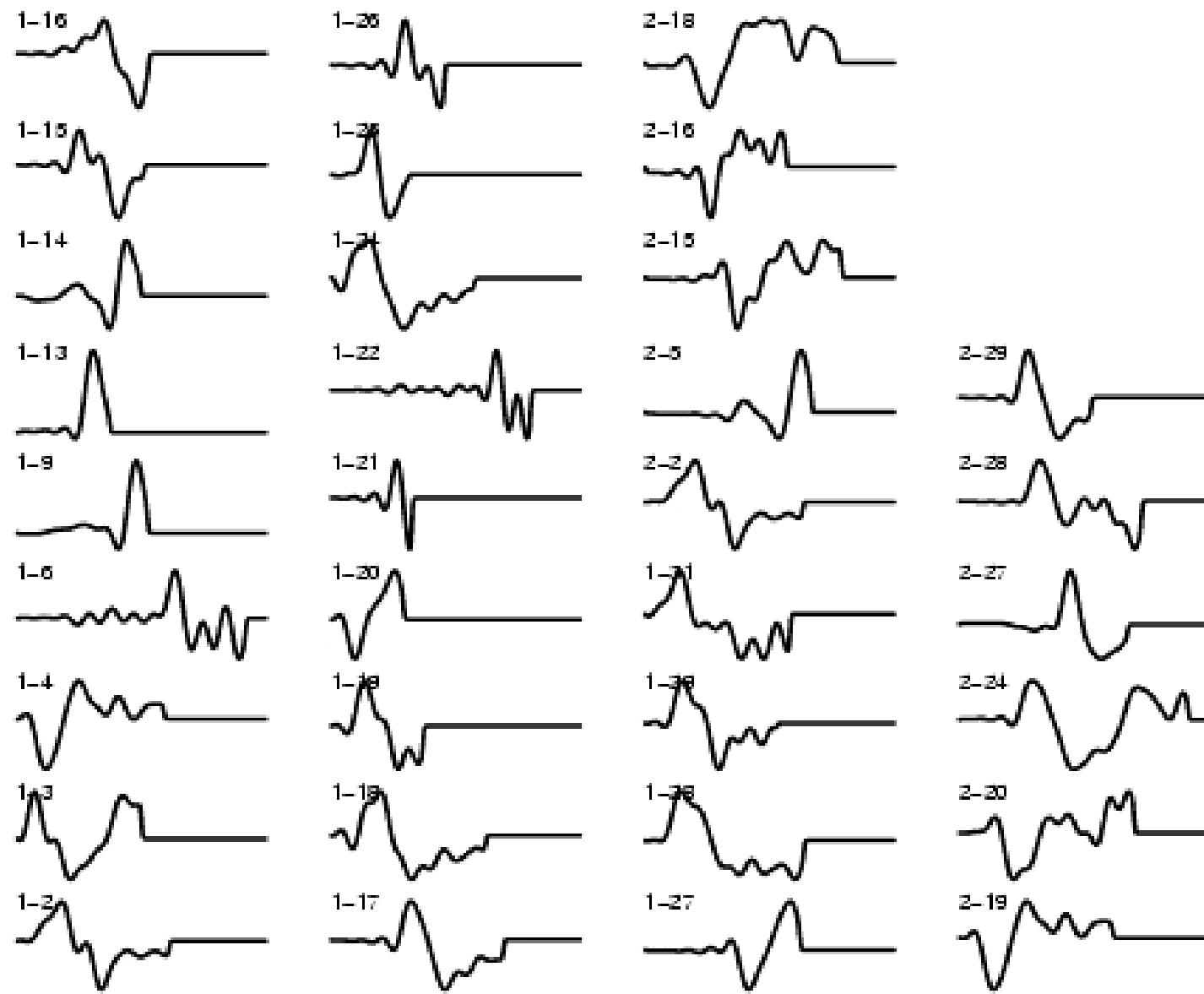
Scalar Moment



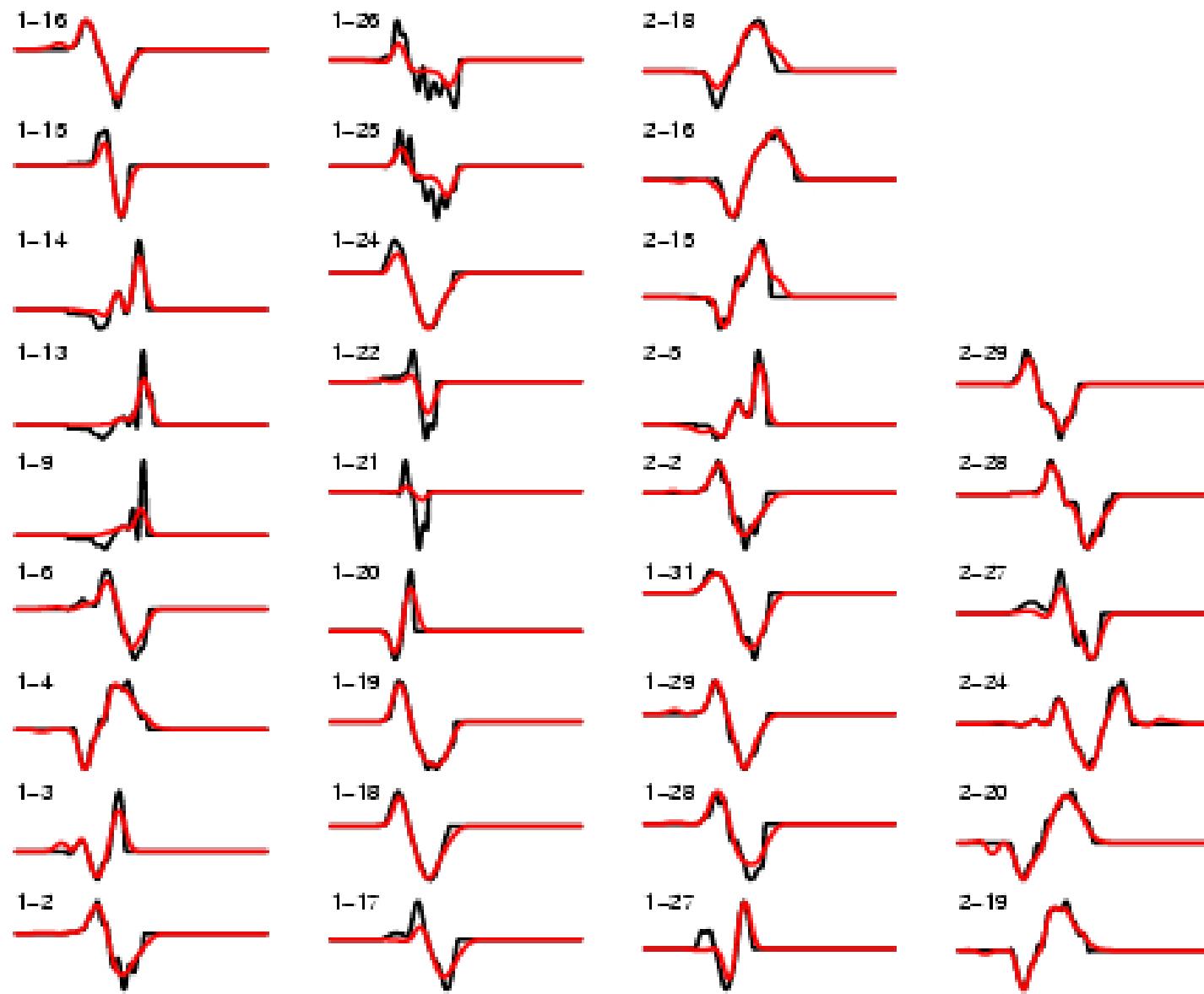
Root Mean Squares Residua



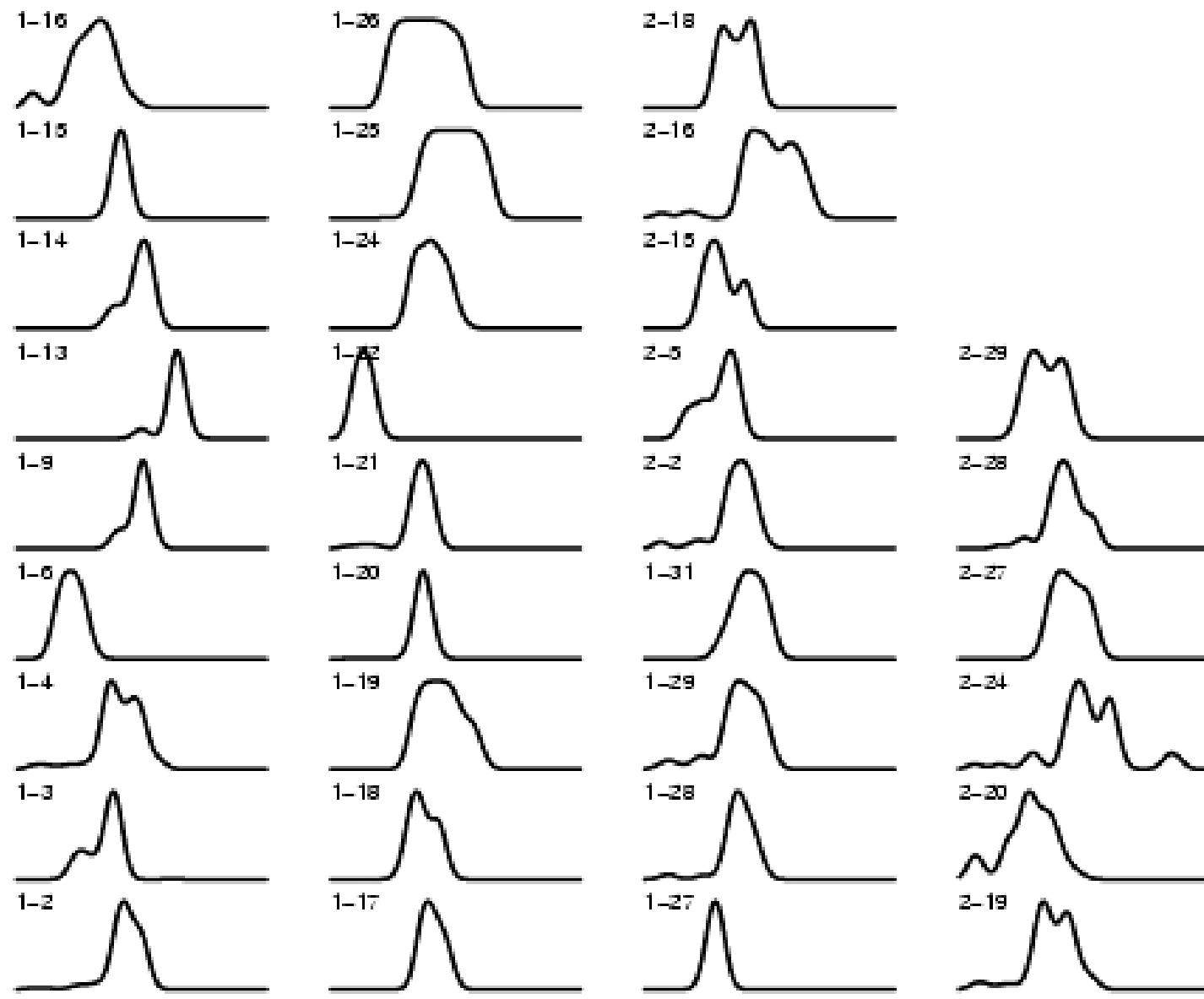
Empirical Green Functions



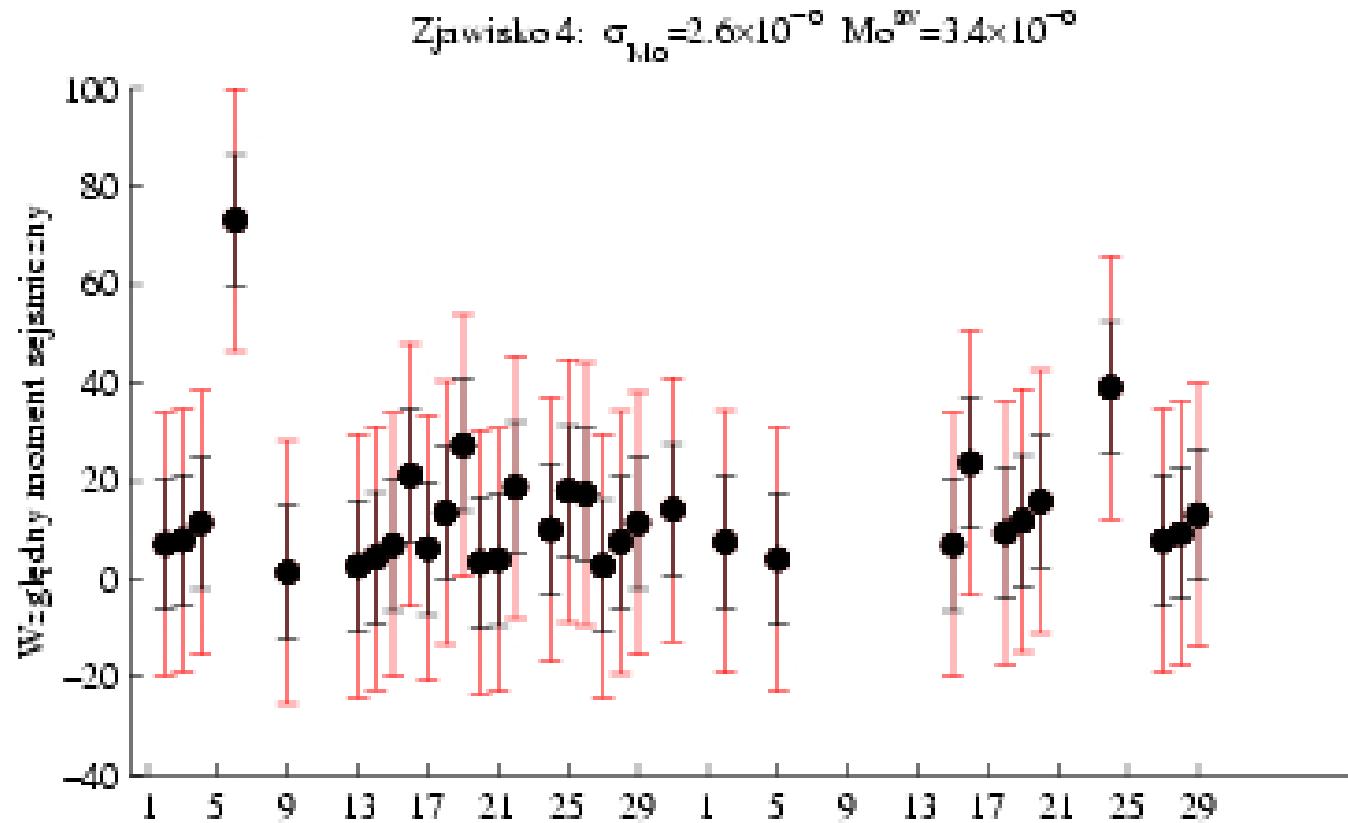
Synthetics/Main



Source Time Function



Scalar Moment



Root Mean Squares Residua

